

ERDF UOMARI – New technologies for channel and mine pool mapping

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UOMARI – Uudet teknologiat uomien ja kaivosaltaiden kartoitukseen

Project time

10/2023–03/2026

Budget

666 942 €

EU-funding

553 551 €

Geological Survey of Finland (GTK)

University of Oulu - The Unit of
Measurement Technology (MITY)

Finnish Environmental Institute
(SYKE)

Finnish Geospatial Research Institute
(MML)



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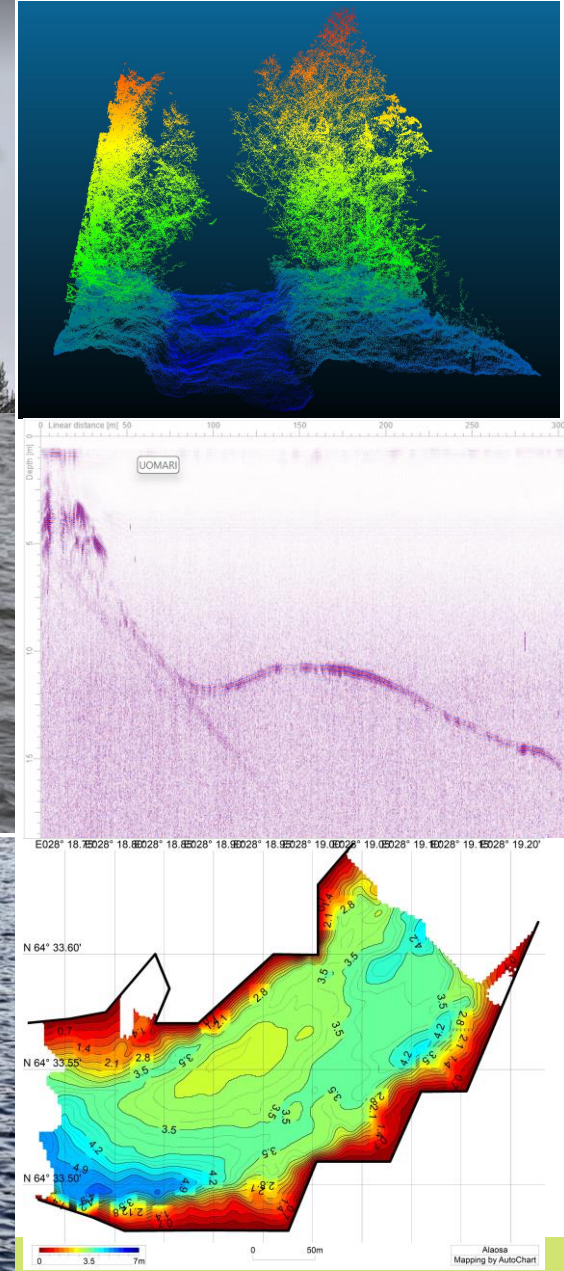
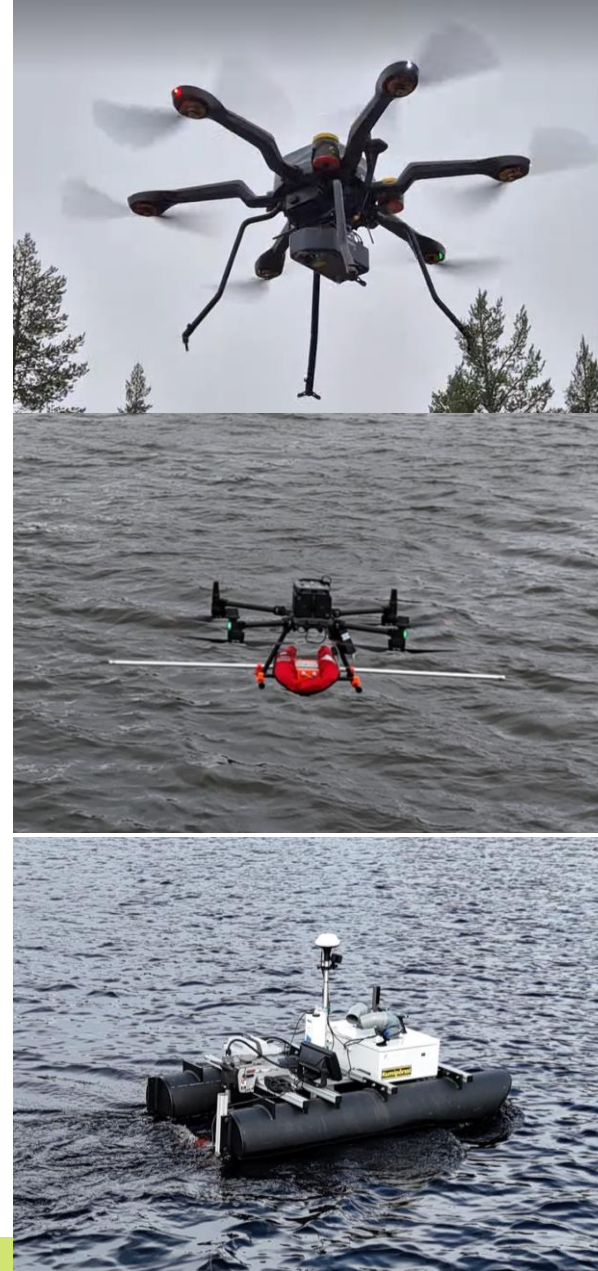


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Project goals:

- Develop and pilot new cost-effective drone-integrated measurement- and imaging technologies for channel and mine pool mapping
 - Two wave length laserscanner drone-solution - MML
 - GPR-drone (GPR + drone) – OY MITY
 - Autonomous survey vessels for water - SYKE
- Develops data management for multiple imaging methods (LiDAR, GPR, FLIR, RGB)
- Compare developed imaging methods with traditional measurement methods



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- There are thousands of kilometers of channels in Finland that have been modified for various purposes.
 - Mapping is becoming more relevant as watercourse restoration and mire restoration increase.
 - The bottom shapes of riverbeds affect, among other things, the flow and thereby the mixing of industrial discharge waters.
- Pool structures consist of many different layers, the functionality and condition of which is challenging to determine in use.
 - The causes of recent environmental accidents have often been problems related to the bottom membrane and bottom structures.
 - In old mining areas there is often no information about thicknesses, materials, properties, etc.
- Mapping underwater bottom data is very labor-intensive and slow, and sometimes also risky.

→ *The need for new cost-effective measurement and imaging methods*



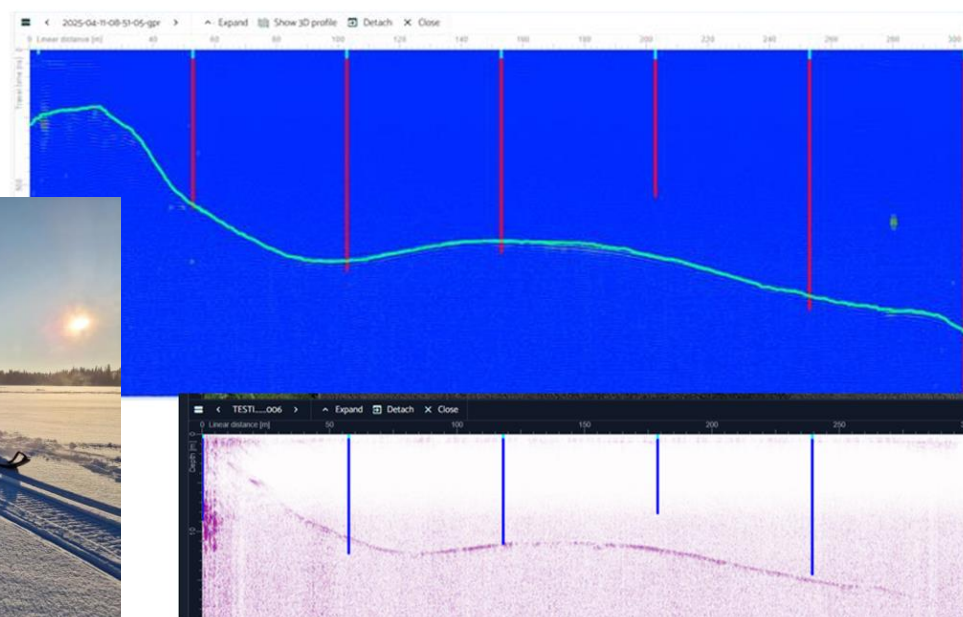
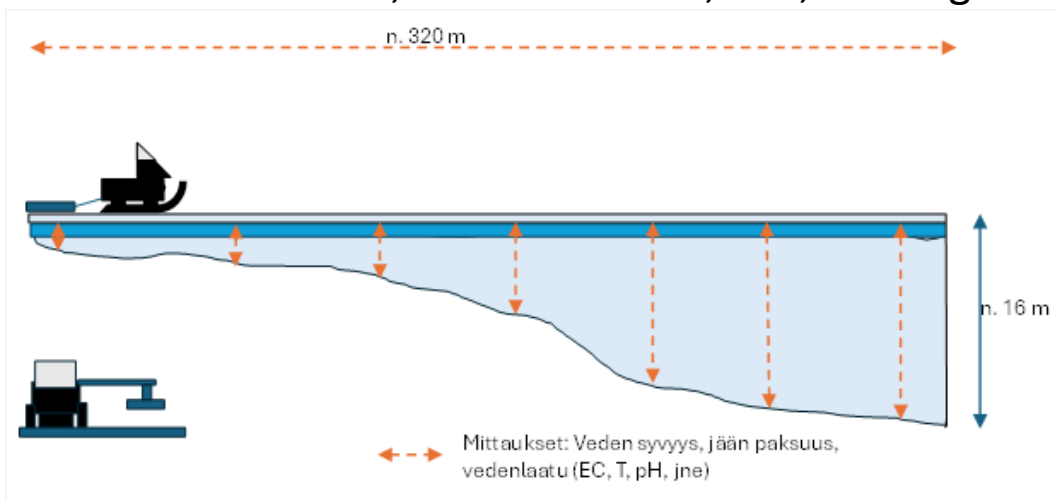
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- Ease the planning of riverbed restoration projects and monitoring of impacts
- Ease the assessment of environmental impacts, e.g. in the planning of mine water discharge routes
- Reducing environmental harm and risks from business activities
- Increasing occupational safety and cost-efficiency
- Creating operating conditions and business opportunities for companies that rehabilitate and map the environment



Bottom shape with a GPR-drone and a sonar raft

- Comparing test data obtained with drone measurement systems and traditional measurement methods
 - ADCP-rafts, flow tracker, traditional GPR (on foot, snow mobile), GEM-2
- The usability of the developed methods for various types of applications, such as mixing models, ecological impact assessment, habitat models, etc., is being investigated.



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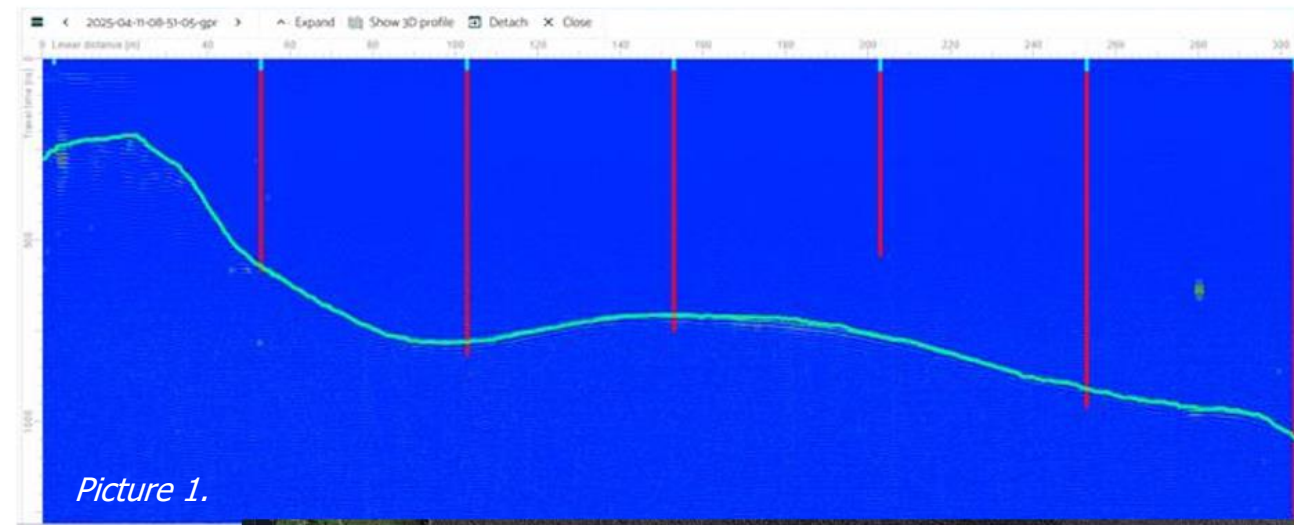
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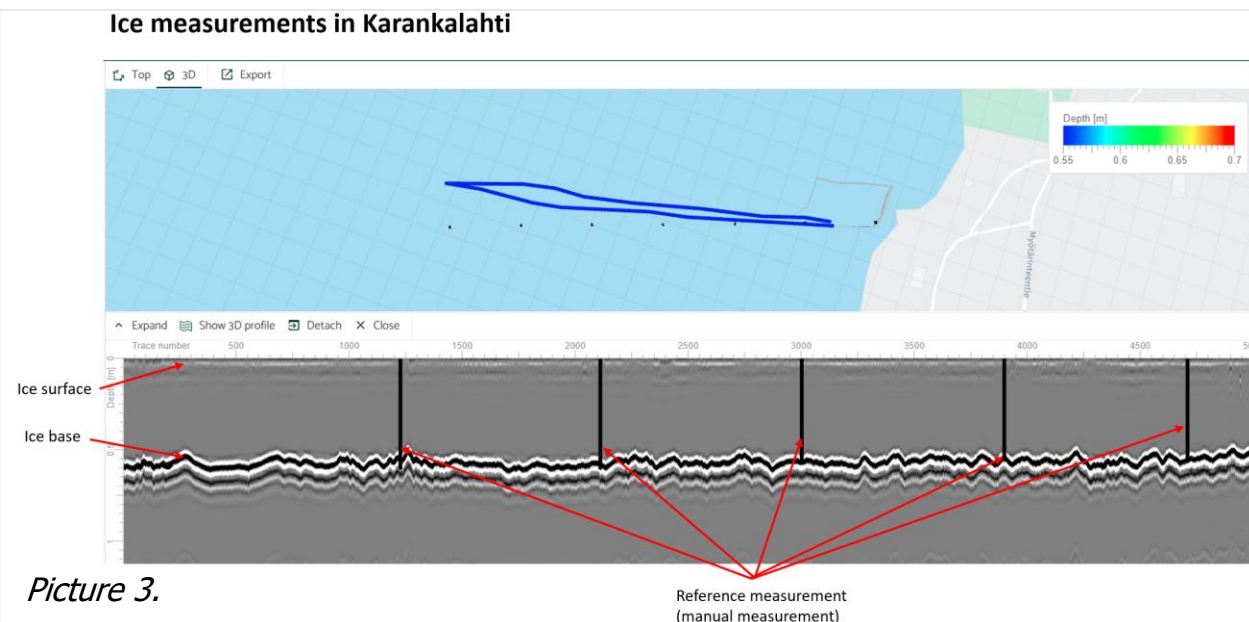
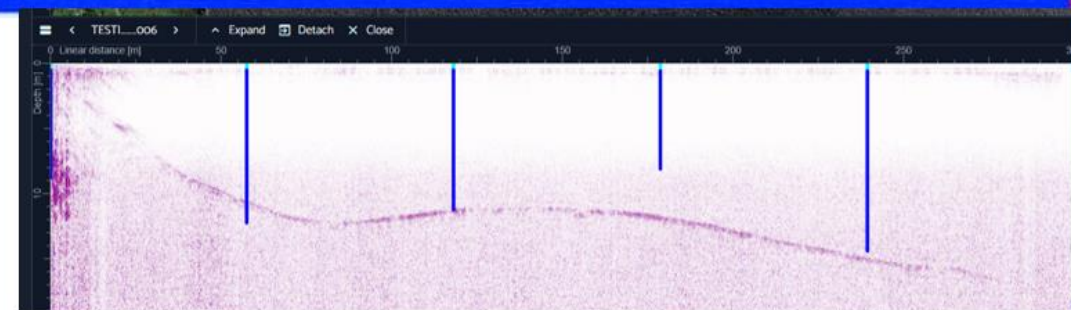
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Testing and comparison measurements of GPR ground penetrating radars in Karankalahti (results)

- Bottom shape with drone + GPR 100 MHz (Picture 1)
- Bottom shape with traditional 100 MHz GPR (Picture 2)
- Ice thickness with drone + GPR 1000 MHz (Picture 3)
- Results:
 - The acquired low-frequency radar shows the bottom shape well, although it differs at a few comparison points.
 - The acquired high-frequency radar clearly shows the ice thickness



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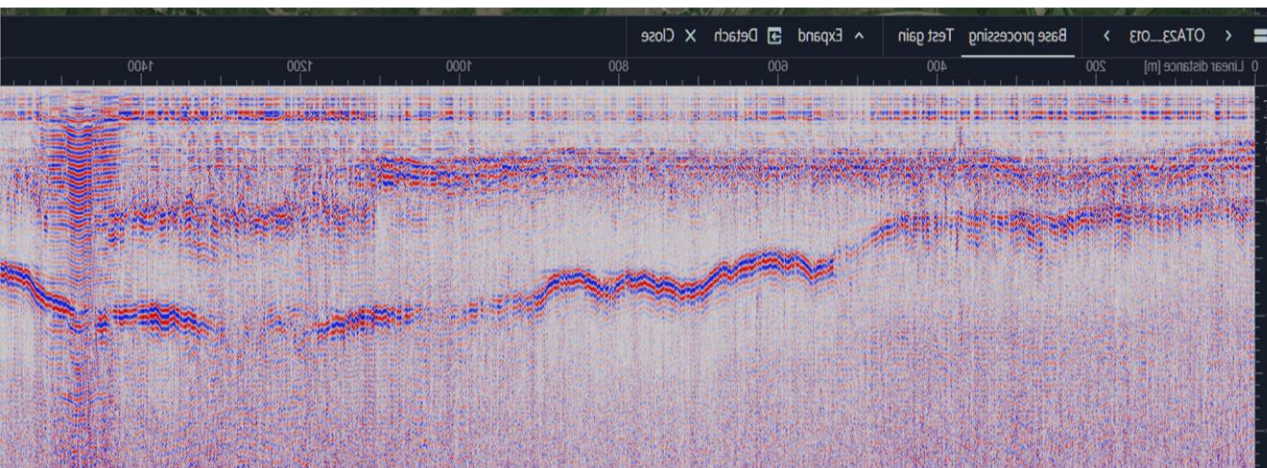


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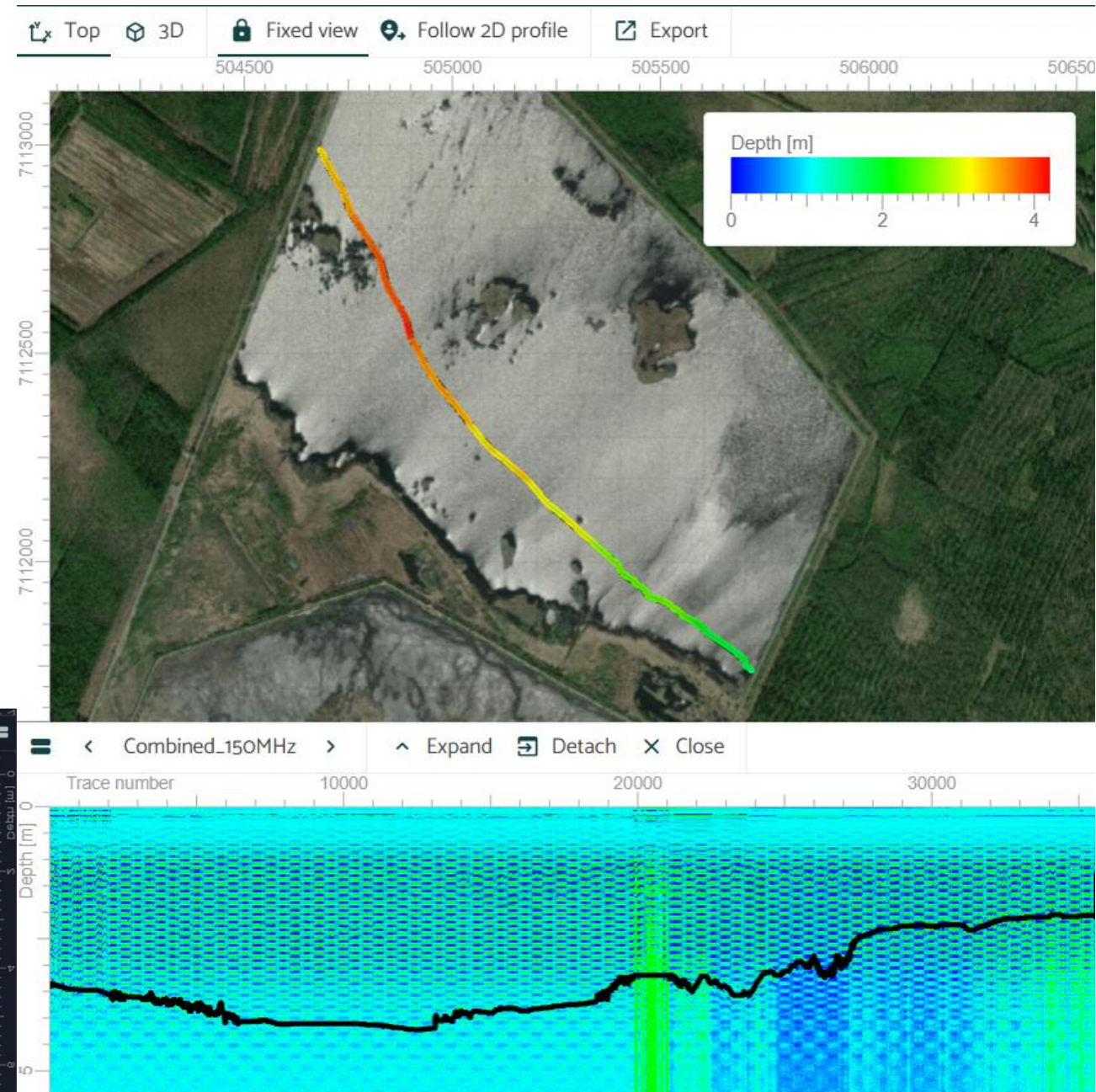
Piloting new technologies for mapping mine pools

Otanmäki mine drone measurements vs traditional GPR

- For comparison, the 2023 traditional ground-based radar measurement (100MHz, image flipped into a mirror image) matches each other very well



Kuva 1. Pohjanmuoto lintuvesialtaalla perinteisellä maatutkalla (moottorikelkalla vedetty)

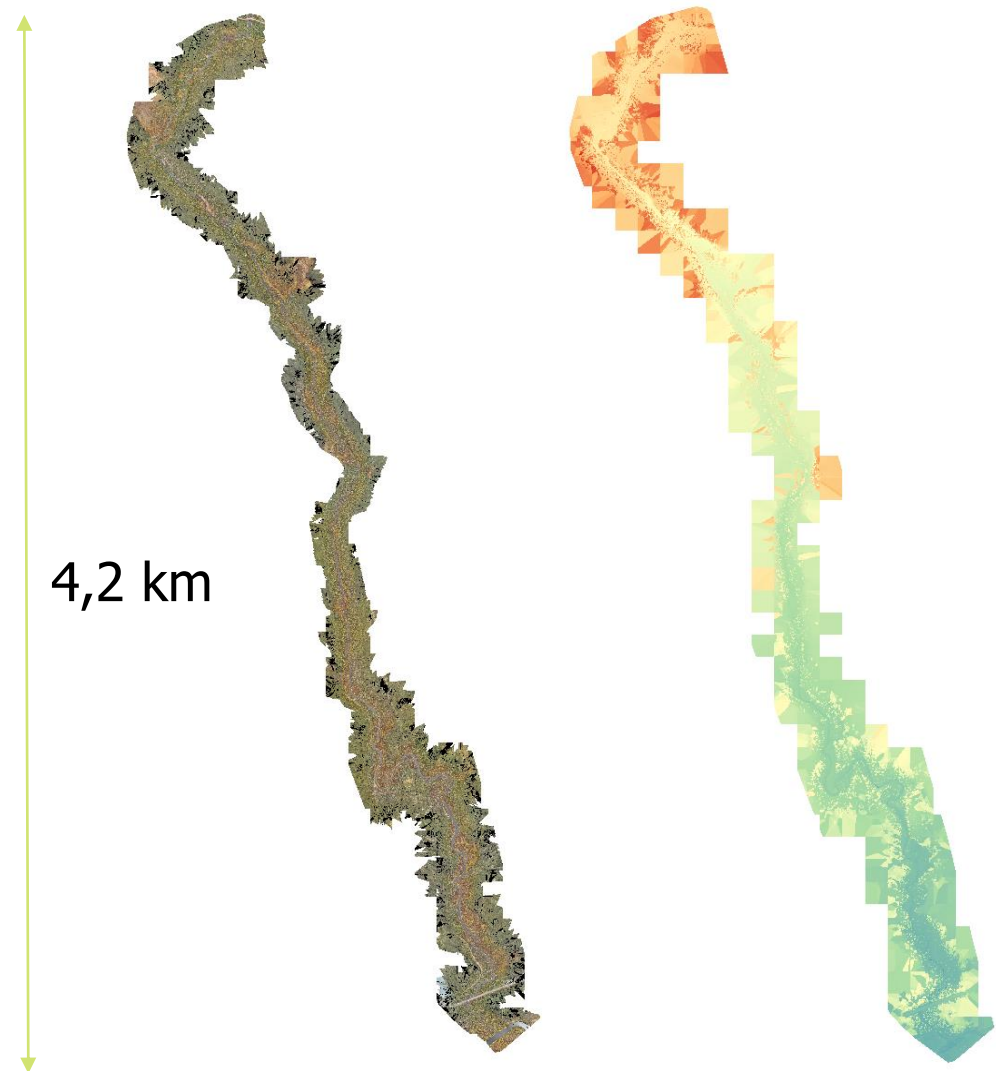


Kuva 2. Pohjanmuoto lintuvesialtaalla dronemittauslinjalta

Piloting new technologies for riverbed mapping

Hannukainen, Kolari

- Fieldwork during may and september 2024
 - RGB+IR imaging
 - 2 wavelenght laser scanning
 - Traditional measurements



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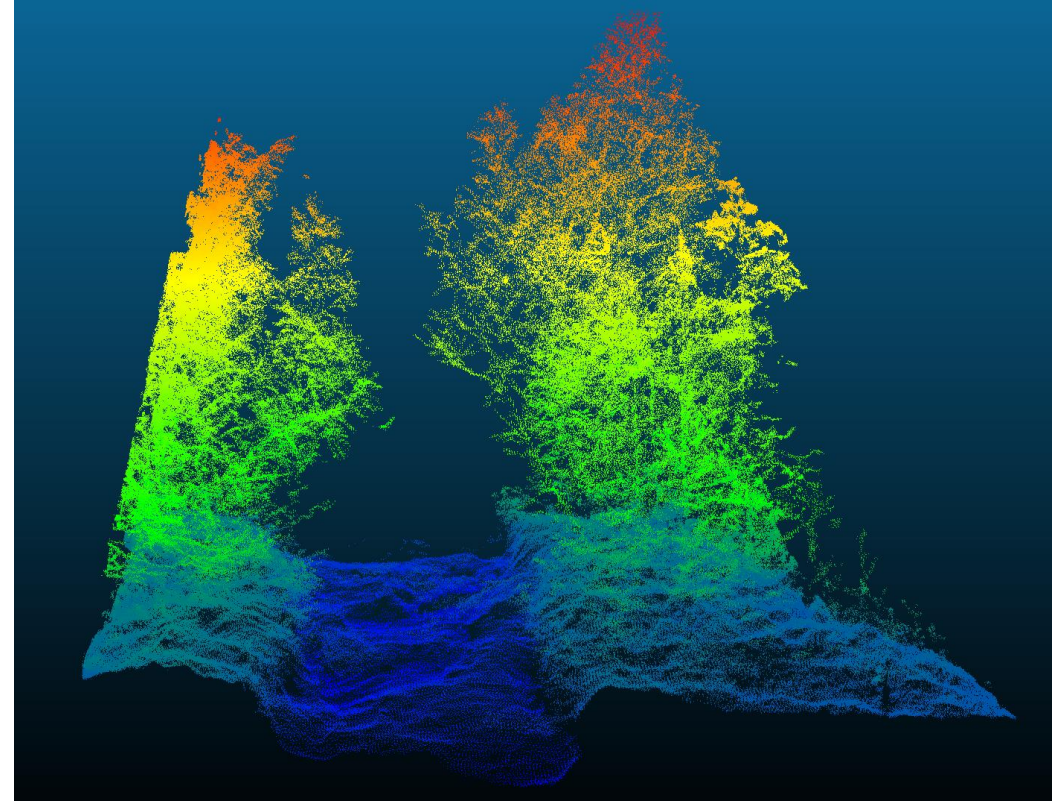
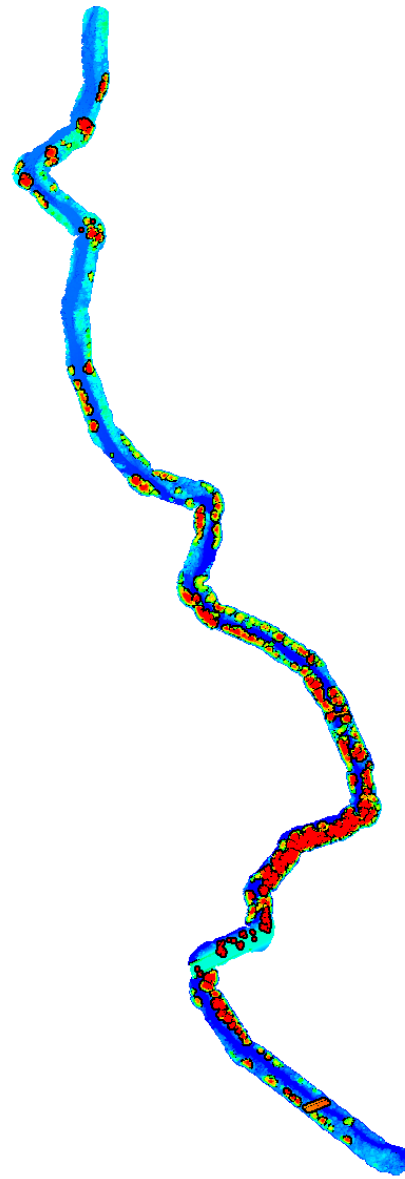


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Two wavelength laser scanning

Hannukainen, Kolari

- Two wavelength laser data from river Valkeajoki



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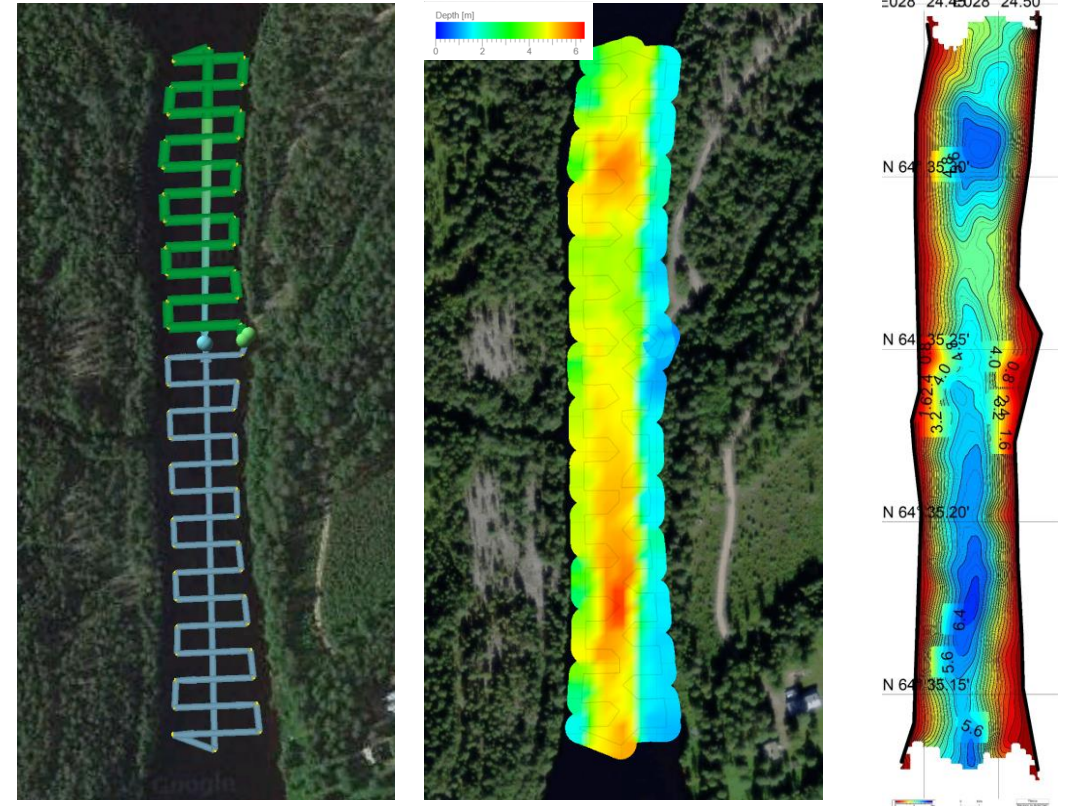


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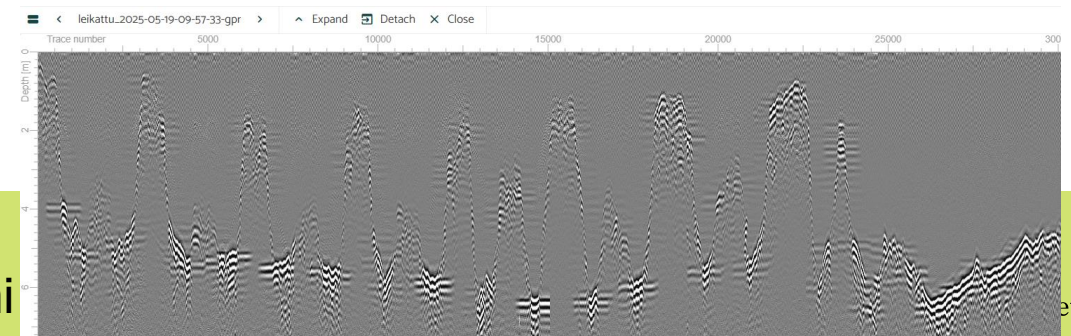
Channel and mine pool mapping - UOMARI

Emäjoki, Ristijärvi

- Drone 350 RTK + GPR LF flights 19.5.2025
- Flight route (Picture 1, left)
- Depth map from GPR-data (Picture 1, middle)
- Depth map by Finnish Environment Institute with an autonomous raft's sonar (Picture 1, right)
- Picture 2: example of GPR signal



Picture 1



Picture 2.

Kiitos!

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